

Smart Motorways: how did we get here, where are we, and what do we know about safety?

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- The Tesla manual explains, "Traffic-Aware Cruise Control cannot detect all objects and may not brake/decelerate for stationary vehicles, especially in situations when you are driving over 50mph and a vehicle you are following moves out of your driving path and a stationary vehicle or object is in front of you instead."
- Volvo's semi-autonomous system, Pilot Assist, has the same short coming. The manual states: "*Pilot Assist will ignore the stationary vehicle* and instead accelerate to the stored speed".

How did we get here?

Approach:

- Alternative to conventional widening
- Lower cost and faster delivery without DCO
- Equal or better safety performance for users
- Technology enables lane closure, speed reduction and driver information messages supports workers (but note hard shoulder removal raises concerns for Traffic Officers)
- Lane control keeps traffic moving when a lane is closed journey time/reliability benefits
- More resilience (rapid speed control, much faster than TTM and without orders etc)







Smart Motorway features

In all formats:

- Technology to monitor and control flow and speed including lane closures.
 Variable mandatory speed limits (red ring); TTCV; lane control (red X)
- Connection to operations centre control room where cctv is used to monitor once events identified
- Traffic Officer patrol/attendance to promptly deal with obstructions and keep lanes clear

In some formats:

- Hard shoulder conversion to running lane part time/full time (*not permanent or temporary as often described*)
- Stopped Vehicle Detection to reduce duration of live lane stops



The timeline of Smart Motorways



Where are we? 1. Definitions



	Vanilla D3M (conventional)	Controlled Motorway	Dynamic Hard Shoulder	All Lane Running	GD 300 APTR	
Lanes	3 lanes	3 lanes	3 lanes off peak 4 lanes peak	4 lanes	2-3 lanes	
Place of relative safety (PRS)	Hard shoulder 24/7	Hard shoulder 24/7	Off peak hard shoulder, plus Emergency Areas (laybys)	Emergency Areas (laybys)	Emergency Areas (laybys)	
Speed limit (excl TTRO)	70mph	40 to 70mph	40 to 70mph	40 to 70mph	40 to 70mph	
Control centre connection	Yes	Yes	Yes	Yes	Yes	
Traffic Officer coverage	Yes	Yes	Yes Yes		Scheme- dependent	
Stopped vehicle detection (SVD)	Yes	Yes	Yes	Yes	Scheme- dependent	

Where are we? 2. The Network Annex A – Smart motorways map

(correct as of June 2023)

10% of motorway is now DHS or ALR

ALR motorway 3 M1 Junction 13 - 16 M1 Junction 16 - 19 6 M1 Junction 24 - 25 8 M1 Junction 28 - 31 10 M1 Junction 32 - 35a 11 M1 Junction 39 - 42 12 M3 Junction 2 - 4a 1 M4 Junction 3 - 12 16 M5 Junction 4a - 6 10 M6 Junction 2 - 4 (0 22 M6 Junction 11a - 13 23 M6 Junction 13 - 15 24 M6 Junction 16 - 19 26 M20 Junction 3 - 5 28 M23 Junction 8 - 10 30 M25 Junction 5 - 6 35 M25 Junction 23 - 27 37 M27 Junction 4 - 11 41 M56 Junction 6 - 8 (1) M62 Junction 10 - 12 (M62 Junction 18 - 20 M8 Junction 3s to 4 Controlled motorway ALR scheme in construction 25 M6 Junction 21a - 26 ALR schemes cancelled 13 M3 Junction 9 - 14 3 M25 Junction 10 - 16 38 M40 - M42 interchange 4 M62 Junction 20 - 25



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This map is intended to provide a high level representation of the smart motorway

How safe is it? 1. Modelled & actuals *before* ALR implemented



 Built from a combination of experience, empirical evidence and simulation;

 ALR showed approximately 15% reduction in risk compared to baseline (D3M without MIDAS)
– effectively nil detriment safety effect to achieve higher capacity

How safe is it? 1. Big picture of hazards – and ethics of net gain



Relationship between risk and collision data

a) Change in risk from all hazards vs change in collisions of all types



Figure 4-10 Manhattan charts based on the overarching STATS19 dataset

- Data supports safety case for all SM forms inc ALR
- Live lane breakdowns occur less often than predicted ; they account for a minority of fatal collisions.
- Most collisions caused by human error not breakdown (as elsewhere)

Eye tracking: drivers attend more when no hard shoulder

highways england

Highways England

December 28

Smart Motorway All Lane Running Overarching Safety Report 2019

- 1 stop per refuge per 4 hrs •
- 71% of stops are non-emergency

Drivers' role in safety? Journey preparedness in collision prevention



Over 70% of stops in emergency areas (laybys) are illegal discretionary stops

Rate of 'Live Lane' breakdowns = 0.4 / day per carriageway mile

Of which. . . - 11,200 run out of fuel per annum - 38,700 tyre failures per annum of which approx. 4,700 requires lane closures - 1,650 vehicle fires per

Beliefs versus behaviour: the role of cognitive dissonance and biases



Sample size 21,479.

Figure 6

2019)

What does this mean for messaging and network operation?

Bacobs 2019

How safe is it? 1. Third year stocktake of ALR performance

High level findings:

- Of the 4 formats and many safety metrics, no format is best in all cases
- Live-lane-stops account for just 3.9% collisions
- 96.1% involve only moving vehicles.

Full disclosure of all data so independent analysis can be done by any interested party

High level findings: ALR schemes Statistically significant reduction in

- All collisions
- Casualty rates

Reduction in:

- FWI rates
- Most collision types

Lower Live lane stop collision rate than expected

Conventional	Controlled	Dynamic	ALR
Highest KSI collisions			
SVD and more EAs like	collisions [3.9%] (though	Lowest moving-vehicle co	ollisions [96.1%]
Lowest stopped- vehicle-collison rate			Highest stopped vehicle collision rate (likely to fall with SVD)



How safe is it? 1. Third year stocktake of ALR performance – stopped vehicle collisions



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Personal injury collision rates (stopped vehicles) - Confidence intervals

How safe is it? 1. Third year stocktake of ALR performance – moving vehicles (96.1% PICs)



Collision rate (moving vehicles)

Basket of metrics – priority for most severe injury

Table 1

Headline five-year average (2017-2021) injury-adjusted metrics per road type⁵¹

Description: Across all collisions, all three types of smart motorway continue to be better than conventional motorways for those metrics which consider the most significant impacts, such as deaths or serious injuries Source: Analysis from National Highways Data based on STATS19 with minor amendment⁵²

		PIC	PIC per hmvm	FWI	FWI per hmvm	KSI	KSI per hmvm
	Conventional	2,423	5.67	155	0.36	615	1.45
Types of motorway	ALR	335	5.99	20	0.35	82	1.43
	DHS	219	7.32	9	0.31	34	1.14
	Controlled	534	7.76	21	0.31	90	1.31
A-roads (on SRN)		4,045	12.59	286	0.89	1,172	3.65

Delivering improvements - progress made on 2020 Action Plan



Customer perceptions of smart motorways



All-lane running smart motorways The driver's view December 2020

transportfocus

Key points emerging from the research

- Many drivers will continue to believe, even if they feel safe on a smart motorway, that they would be even safer with a hard shoulder.
- The visible, physical hard shoulder has been taken away, but the individual compensating features are less visible and aren't viewed as part of an overall system working to keep drivers safe.
- Drivers are conscious that if they break down, their safety is dependent on others following the rules and they see too many people ignoring them, in particular the 'red X'.

Survey of 20,000 people including people who don't drive on SM

- 54% fairly or very confident on SM
- 25% not very/not at all confident on SM

For those who do drive on SM

- 82% fairly or very confident on SM
- Therefore experience offsets instinctive fear of LLS (which dominates anxiety but is <4% collisions)

Likelihood of nervous drivers not using the safest roads for their journeys (TSC evidence) – media hold responsibility for misreporting



Overstated journey benefits: do they affect safety?

Time saving benefits of M25 upgrade 'eaten up by growth'

Roads

19 April 2021



The extra capacity created by a smart motorway scheme on the M25 was quickly eaten up by traffic growth, which eliminated the time saving benefits used to justify the investment, says a new research paper.

M25: all-lane running near Junction 25 David Metz, honorary professor at the Centre for Transport Studies, University College London, has explored the effect of Highways England's project to convert the hard shoulder into a running lane between junctions 23 and 27 of the M25.

The M25 traffic model used to justify the smart motorway investment substantially underestimated this increase in traffic volume, while overestimating the average increase in speed for most drivers, put at about 10 km per hour. The benefit-cost ratio was estimated to be 2.9, that is, £2.90 of economic benefit for every £1 invested. Since the travel time savings didn't last beyond the first year after opening, the actual benefit-cost ratio was much lower.

SM-ALR Monitoring

M25 J23-27 Second Year Evaluation Report Highways England

March 2017



M25 J23-J	27	
Flows	J23-6: Significant (10%) flow increase achieved and capacity for more growth In particular 17% J24-25 CW. All higher than national trends.	
Average journey time	JTs returned close to pre-scheme levels but have been worse if scheme not built. CW 3% increase overall, ACW 0.5% decrease.	\Leftrightarrow
Journey time reliability	Slight improvement day-to-day on both carriageways	$\widehat{\mathbf{t}}$
Safety	No significant change after taking into account background trends. Scheme has met its safety objectives.	\Leftrightarrow

Future-proofing – how might driver-assistance and highly automated vehicles change SM safety?

Intelligent Speed Assistance

- © Reduce speed variance
- © Reduce % above speed limit and enforceable threshold

Lane Keep Assist?

? Will it be better or worse than humans at reading tramlines?

Autonomous braking

- © reduce shunts
- ¹ It doesn't always work; potential for over-trust

electronically-locked headway versus human-judged Sub-conscious behaviours: herd effects

Distance between vehicles in platoons Total platoon length: in 128,147 m in Distance between 0.3 s in THW03 and 1.4 s in THW14 THW03 and 129.181 m in THW14 platoons: 2.2 s / 55 m start \rightarrow Four platoons (55.92 mph) Lead (1) (57.79 mph) and 111 'Ego' Other fast traffic 000 0.70 (87 mph) Platoon nº 1 Platoon nº 2 16 min. - stop 1 min.

Tesla In Taiwan Crashes Directly Into Overturned Truck, Ignores Pedestrian, With Autopilot On

Brad Templeton Senior Contributor @ over robocar technology & previously worked on Google's car team

Video from Taiwan reveals a disturbing Tesla TSLA +0.4% crash, where the vehicle plows directly into the top of a large truck lying on its side, straddling two lanes of a freeway. The driver states the vehicle was in Autopilot mode. The driver did not hit the brakes himself until far too late, indicating he was probably not paying attention. The road has light traffic and visibility is very good. Nobody was injured





Mixed fleet is

worst case

If you have been, thanks for listening!

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M62 junction 30 dynamic hard shoulder motorway